

FIG. 1

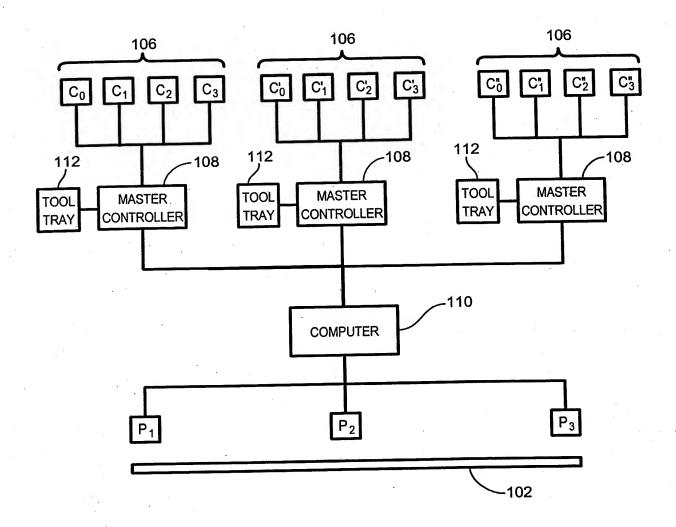
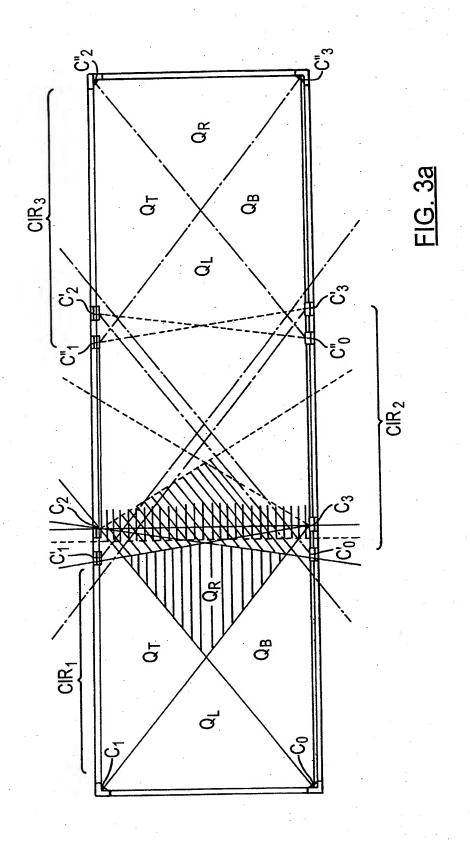
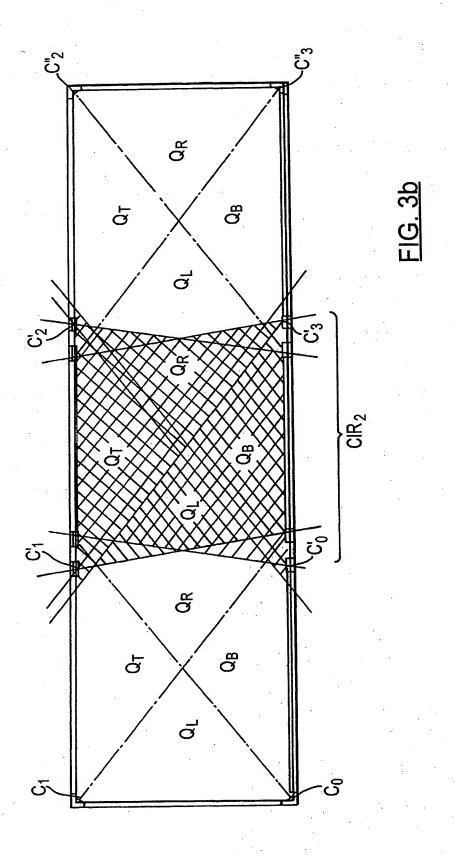


FIG. 2





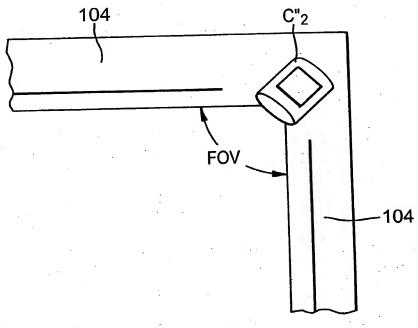
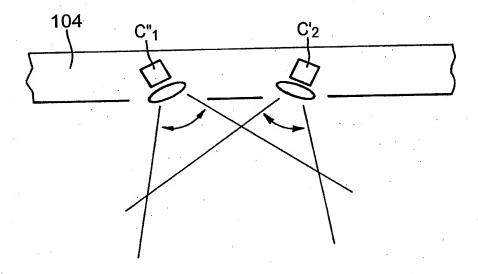
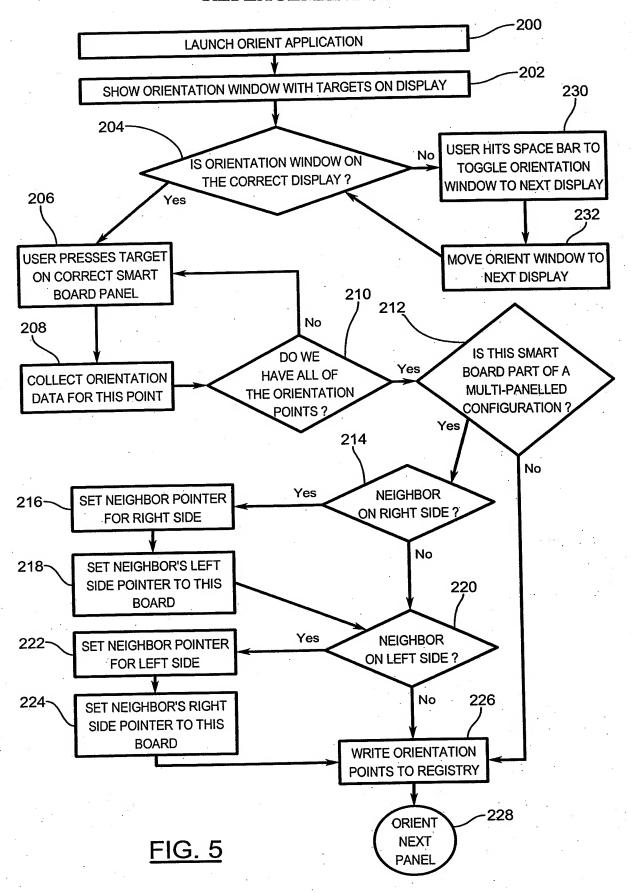
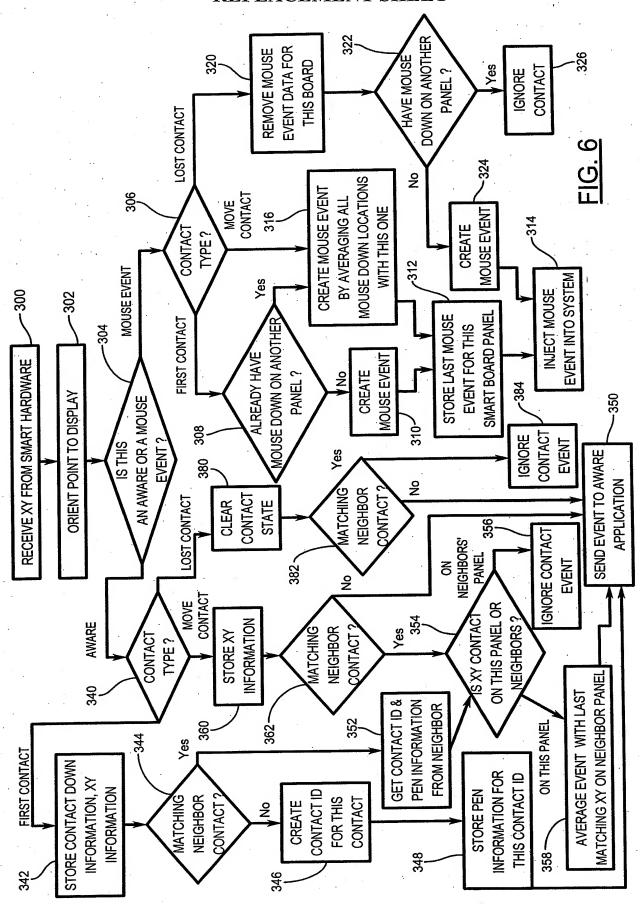


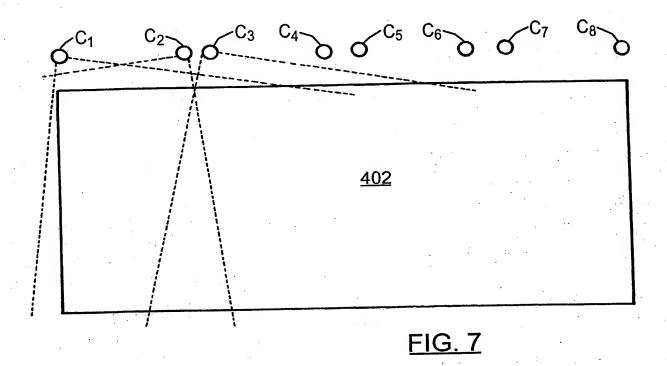
FIG. 4a

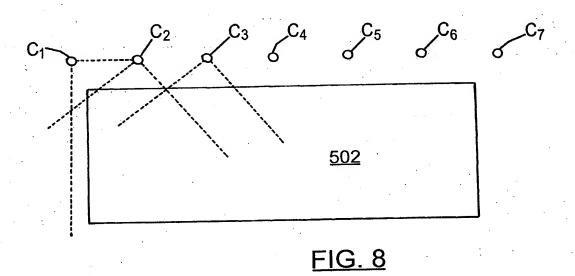


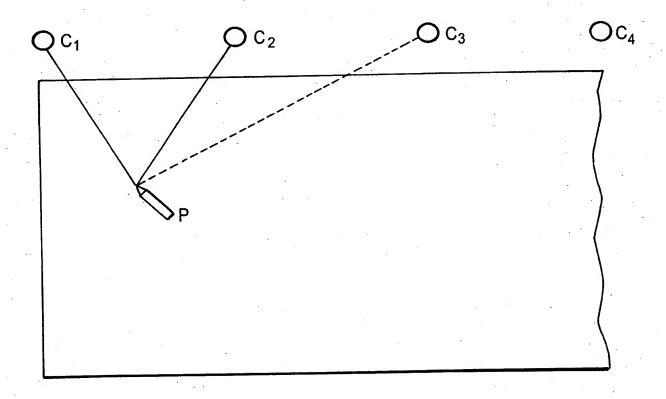
<u>FIG. 4b</u>











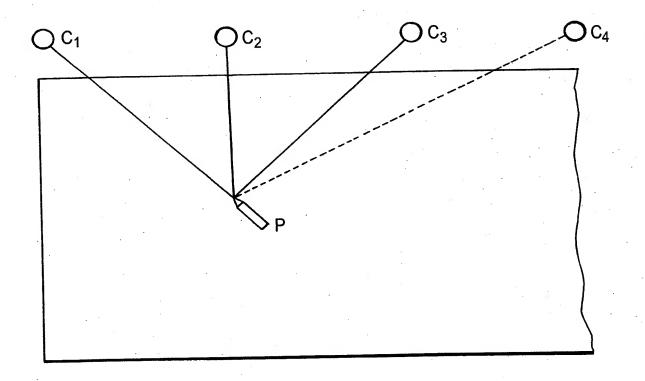
PRIMARY TRIANGULATION PAIR:  $C_1 + C_2$  CAMERA  $C_3$ MAY SEE POINTER P

C<sub>3</sub>MAY:

- IGNORE POINTER P (TOO FAR AWAY)
- PASSIVELY TRACK POINTER P
- ASSIST IN TRIANGULATION OF POINTER P

 $(C_1 + C_3, C_2 + C_3)$ 

FIG. 9a



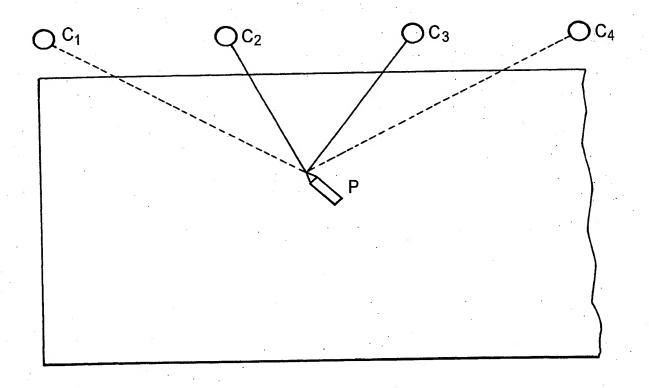
PRIMARY TRIANGULATION PAIRS:  $C_1 + C_2$ ,  $C_1 + C_3$ ,  $C_2 + C_3$  CAMERA  $C_4$  MAY SEE POINTER P

C<sub>4</sub>MAY:

- IGNORE POINTER P (TOO FAR AWAY)
- PASSIVELY TRACK POINTER P
- ASSIST IN TRIANGULATION OF POINTER P

 $(C_1 + C_4, C_2 + C_4, C_3 + C_4)$ 

FIG. 9b



PRIMARY TRIANGULATION PAIR: C<sub>2</sub>+ C<sub>3</sub> CAMERAS C<sub>1</sub> AND C<sub>4</sub> MAY SEE POINTER P

- C<sub>1</sub>& C<sub>4</sub>MAY: IGNORE POINTER P (TOO FAR AWAY)
  - PASSIVELY TRACK POINTER P
  - ASSIST IN TRIANGULATION OF POINTER P

 $C_1 + C_2$ ,  $C_1 + C_3$ ,  $C_1 + C_4$ 

C<sub>2</sub>+ C<sub>3</sub>, C<sub>2</sub>+ C<sub>4</sub>

C<sub>3</sub>+ C<sub>4</sub>

FIG. 9c